

Point counting Algorithms

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1 Preliminaries

Suppose

$$V = \{(x_1, x_2, \dots, x_u) \mid 1 \leq x_i \leq n, x_i \in \mathbb{N}, i = 1 \dots u\}$$

Define $X_i(I) = i^{\text{th}}$ coordinate of I for $I \in V$. A **cost function** $C : V \rightarrow \mathbb{R}_+$ is defined as $C((x_1, x_2, \dots, x_u)) = \sum_{i=1}^u C_{x_i}$. for some constants $C_i \in \mathbb{R}_+$ with $C_i \leq C_j$ for $i \leq j$.

Suppos T is any positive constant.

Definition 1.1 Suppose $I, J \in V$. **Distance** d of I, J is $d(I, J) = \sum_{j=1}^u |X_j(I) - X_j(J)|$. I, J are called **neighbors** if $I \neq J$ and $|X_k(i) - X_k(j)| \leq 1$ for all k , $1 \leq k \leq u$. We say that J is a **smaller neighbor** of I if $X_k(J) = X_k(I) - 1$ for exactly one value of k . $(1, 1, \dots, 1)$ does not have a smaller neighbor. A point $P \in V$ is called an **anchor point** if $C(P) \geq T$ and if P has a smaller neighbors, then there exist a smaller neighbors P_0 with $C(P_0) < T$. We will say that P_0 **defines** P . The set of anchor points is denoted by \mathfrak{A} . A subset X of V is called **connected** if for any $I, I' \in X$, $\exists I_1, I_2, \dots, I_r \in X$ such that I is a neighbour of I_1 , I_r is a neighbour of I' and I_j is a neighbour of I_{j+1} for $1 \leq j < r$. We also say that $\{I_1, \dots, I_r\}$ is a connected path from I to I' .

Let $\sigma \in S_u$ be a permutation. We define $\sigma((x_1, \dots, x_u)) = (x_{\sigma(1)}, \dots, x_{\sigma(u)})$. We record some elementary properties in the following lemma.

Lemma 1.2 Suppose $\sigma \in S_u$ and $I, J, P, Q \in V$. Then yhe following hold.

1. $C(\sigma(I)) = C(I)$ for all $I \in V$.
2. If Q is a neighbor of P then $\sigma(Q)$ is a neighbor of $\sigma(P)$.
3. If $P \in \mathfrak{A}$, then $\sigma(P) \in \mathfrak{A}$. In other words, \mathfrak{A} is stable under S_u .
4. $d(P, Q) = d(\sigma(P), \sigma(Q))$.
5. If $S \subset V$ is connected, then $\sigma(S) = \{\sigma(I) \mid I \in S\}$ is also connected.

Proof If $P \in \mathfrak{A}$ and P_0 is a defining small neighbor of P then $\sigma(P_0)$ is a defining small neighbor of $\sigma(P)$. ■

Theorem 1.3 *If $P \in \mathfrak{A}$ and $P \notin \{(1, \dots, 1), (n, \dots, n)\}$. Then at least one neighbor of P is in \mathfrak{A} .*

Proof Suppose P_0 defines P . By Lemma ??, we can assume that $X_1(P_0) = X_1(P) - 1$ and $X_i(P_0) = X_i(P)$ for $i > 1$. Set $Q = (X_1(P_0), X_2(P_0) + 1, X_3(P_0), \dots, X_u(P_0))$. Clearly Q is a neighbor of P . If $C(Q) \geq T$, then Q is an anchor point as P_0 is the defining smaller neighbor of Q . On the other hand, if $C(Q) < T$, then $Q' = (X_1(P_0) + 1, X_2(P_0) + 1, X_3(P_0), \dots, X_u(P_0)) \in \mathfrak{A}$ as Q is the defining smaller neighbor of Q' . Note that Q and Q' both are neighbors of P . This completes the proof. ■

Lemma 1.4 *Suppose $P, P' \in \mathfrak{A}$ are such that $X_j(P') = X_j(P) + r_j \forall j, 1 \leq j \leq u$ for some nonnegative $r_j \in \mathbb{N}$ and suppose Q is in V with $X_j(P) \leq X_j(Q) \leq X_j(P')$. Then at least one $r_j = 0$ and $Q \in \mathfrak{A}$.*

Proof Suppose P'_0 defines P' . Then for some i ($1 \leq i \leq u$), $X_i(P'_0) = X_i(P') - 1$. Clearly, $r_i = 0$. Define P_1 as $X_j(P_1) = X_j(P'_0)$ and $X_i(P_1) = X_i(P'_0) + 1$. It is now easy to show that P'_0 defines P_1 . This completes the proof.

Corollary 1.5 *Suppose $I, J \in V$ with $X_k(I) > X_k(J) \forall k, 1 \leq k \leq u$. If $I \in \mathfrak{A}$ then $J \notin \mathfrak{A}$.*

Proof We set $r_j = X_j(I) - X_j(J)$ and apply Lemma 1.4 ■

Lemma 1.6 *Suppose $I, J \in V$ are neighboring points such that $C(I) < T$ and $C(J) \geq T$. Then either $J \in \mathfrak{A}$ or there is $P \in \mathfrak{A}$ which is a neighbor of I and J .*

Proof If $d(I, J) = 1$, then I defines J and so $J \in \mathfrak{A}$. Since $C(I) < C(J)$, we can find the smallest index i such that $X_i(I) < X_i(J)$. Define I_1 as follows: $X_j(I_1) = X_j(I)$ for $j \neq i$ and $X_i(I_1) = X_i(I) + 1 = X_i(J)$. Note that $d(I_1, J) < d(I, J)$. If $C(I_1) \geq T$, then $I_1 \in \mathfrak{A}$ and the proof is complete. If $C(I_1) < T$, then we define I_2 taking I_1 for I in the above construction. Note that still I_2 is a neighbor of I and J . If I_2 is not in \mathfrak{A} , we define I_3 and so on. Since $d(I_i, J) < d(I_{i-1}, J)$, this process will stop. ■

Corollary 1.7 *Suppose X is any connected set that contains points I, J such that $C(I) < T$ and $C(J) \geq T$, then X contains an anchor point or X contains a neighbour of an anchor point.*

Proof Let I_1, I_2, \dots, I_r be a connected path from I to J . Since $C(I) < T$ and $C(J) \geq T$, there exists i such that $C(I_i) < T$ and $C(I_{i+1}) \geq T$, where $I_{r+1} \equiv J$. Now we apply Lemma 1.6. ■

Theorem 1.8 *The set \mathfrak{A} of anchor points is connected.*

Proof Suppose P and Q are in \mathfrak{A} with $d(P, Q) = d$. We use induction on d . $d = 1$ is clear. Assume that $d > 1$. Suppose P_0 defines P . We can assume that $X_1(P_0) = X_1(P) - 1$.

Case I: $X_1(P) < X_1(Q)$

By Lemma 1.5 $\exists k$ such that $X_k(P) > X_k(Q)$. Set $P' = (X_1(P), \dots, X_k(P) - 1, \dots, X_u(P))$. Clearly $d(P', Q) < d$. If $C(P') \geq T$, then $(X_1(P) - 1, \dots, X_k(P) - 1, \dots, X_u(P))$ defines P' and the proof is complete. On the other hand, if $C(P') < T$ take $P'' = (X_1(P) + 1, \dots, X_k(P) - 1, \dots, X_u(P))$, then P' is a smaller neighbor of P'' . If $C(P'') \geq T$, then $P'' \in \mathfrak{A}$. If $C(P'') < T$, then $P_1 = (X_1(P) + 1, \dots, X_k(P), \dots, X_u(P)) \in \mathfrak{A}$ and $d(P_1, Q) < d$.

Case I: $X_1(P) > X_1(Q)$

By Lemma 1.5 there exists a k such that $X_k(P) < X_k(Q)$. Set $P' = (X_1(P), \dots, X_k(P) + 1, \dots, X_u(P))$. Clearly $C(P') \geq T$ and $d(P', Q) < d$. Let $P'' = (X_1(P) - 1, \dots, X_k(P) + 1, \dots, X_u(P))$, then $d(P'', Q) < d$.

If $C(P'') < T$, then $P'' \in \mathfrak{A}$. If $C(P'') \geq T$, then $P'' \in A$.

By induction, we can find a connected path from I to Q . \blacksquare

Let $X = \{(i, i, \dots, i) \in V \mid 1 \leq i \leq n\}$. Then X is a connected set. In applications we generally expect $C(1, 1, \dots, 1) < T < C(n, n, \dots, n)$. Therefore by applying corollary 1.7, we can find an anchor point which is a neighbor to (i, i, \dots, i) for some i . Now using connectedness of \mathfrak{A} and an exhaustive search, we can find all the anchor points. We describe this in the following algorithm.

Once all *anchorpoint* anchor points are found is found we can algorithmically find all the points in V with cost greater or equal to T . First we prove the following theorem

Lemma 1.9 (a) Suppose $(a_1, a_2, \dots, a_u) \in \mathfrak{A}$ is such that

$$a_k = \max\{b_k \mid (a_1, \dots, a_{k-1}, b_k, b_{k+1}, \dots, b_u) \in A\}$$

If $(a_1, \dots, a_{k-1}, a'_k, \dots, a'_u) \in V$ and if $a'_k > a_k$ then $C((a_1, \dots, a_{k-1}, a'_k, \dots, a'_u)) \geq T$.

(b) Suppose (b_1, \dots, b_u) is a point in V which is not an anchor point such that $C((b_1, \dots, b_u)) \geq T$. Then $\exists (a_1, \dots, a_u) \in \mathfrak{A}$ such that,

1. $a_i = b_i$ for $i = 1, \dots, k - 1$, $a_k < b_k$ and,
2. $a_k = \max\{c_k \mid (a_1, \dots, a_{k-1}, c_k, \dots, c_u) \in A\}$

Proof (a) Suppose $C(a_1, \dots, a_{k-1}, a'_k, \dots, a'_u) < T$. Since $a'_k > a_k$, not all $a'_i \geq a_i$, $i = k + 1, \dots, u$. Assume that $a'_{l_i} < a_{l_i}$ for $i = 1, \dots, r$, $k + 1 \leq l_i \leq u$. Now by adding s to a'_{l_i} and checking the cost of a point $(a_1, \dots, a_{k-1}, a'_k, \dots, a'_{l_1} + s, a'_{l_2}, \dots, a'_u)$ we can eventually find a point $v = (a_1, \dots, a_{k-1}, a'_k, \dots, a'_{l_j} + 1, \dots, a'_u)$, such that $C(v) < T$ but $C((a_1, \dots, a_{k-1}, a'_k, \dots, a'_{l_j} + 1, \dots, a'_u)) \geq T$. But then $(a_1, \dots, a_{k-1}, a'_k, \dots, a'_{l_j} + 1, \dots, a'_u) \in A$ with $a'_k > a_k$, which contradicts the maximality of a_k . [9]

(b) We choose $(a_1, \dots, a_u) \in A$, with the properties,

- $a_i = b_i$ for $i = 1, \dots, k - 1$,

- k is the largest value such that any anchor point has first $k - 1$ coordinates equal to b_1, \dots, b_{k-1} ,
- $a_k = \max\{c_k \mid (a_1, \dots, a_{k-1}, c_k, \dots, c_u) \in A \text{ and } a_k < b_k\}$.

We will show that [10] $a_k = \max\{b'_k \mid (a_1, \dots, a_{k-1}, b'_k, \dots, b'_u) \in A\}$

Suppose this is not true. Then, there exists $(a_1, \dots, a_{k-1}, b'_k, \dots, b'_u) \in A$, such that $b'_k > a_k$. Since k is largest so that a_1, \dots, a_{k-1} are the coordinates of the given point $b'_k \geq b_k$.

Consider $v_1 = (a_1, \dots, a_{k-1}, b_k, 1, \dots, 1) \in A$. If $v_1 \in A$, then we have a contradiction (since longest prefix is a_1, \dots, a_{k-1}, b_k and not a_1, \dots, a_{k-1}).

Case I: $C((a_1, \dots, a_{k-1}, b_k, 1, \dots, 1)) < T$

Then we have, $C((a_1, \dots, a_{k-1}, b_k, 1, \dots, 1)) < T$ and $C((a_1, \dots, a_{k-1}, b_k, \dots, b_u)) \geq T$. Then there exists a stage such that $C((a_1, \dots, a_{k-1}, b_k, b_{k+1}, \dots, b_{l-1}, 1, \dots, 1)) < T$ and $C((a_1, \dots, a_{k-1}, b_k, b_{k+1}, \dots, b_l, 1, \dots, 1)) \geq T$. But then $(a_1, \dots, a_{k-1}, b_k, \dots, b_l, 1, \dots, 1) \in A$, a contradiction.

Case II: $C((a_1, \dots, a_{k-1}, b_k, 1, \dots, 1)) \geq T$

Now $(a_1, \dots, a_{k-1}, b'_k, \dots, b'_u) \in A$, and $b'_k \geq b_k$. [11] This implies that

$$T \leq C((a_1, \dots, a_{k-1}, b_k, 1, \dots, 1)) \leq C((a_1, \dots, a_{k-1}, b'_k, \dots, b'_u))$$

Suppose $(a_1, \dots, a_{l-1}, \dots, a_{k-1}, b'_k, \dots, b'_u)$ is a small neighbor of the anchor point $(a_1, \dots, a_{k-1}, b'_k, \dots, b'_u)$, then since

$$C((a_1, \dots, a_{l-1}, \dots, a_{k-1}, b_k, 1, \dots, 1)) \leq C((a_1, \dots, a_{l-1}, \dots, a_{k-1}, b'_k, \dots, b'_u)) < T,$$

$(a_1, \dots, a_{k-1}, b_k, 1, \dots, 1) \in A$ a contradiction.

If $(a_1, a_{k-1}, b'_k - 1, b'_{k+1}, \dots, b'_u)$ is a small neighbor of $(a_1, \dots, a_{k-1}, b'_k, \dots, b'_u)$, then $(a_1, a_{k-1}, b_k - 1, 1, \dots, 1)$ is a small neighbor of $(a_1, a_{k-1}, b_k, 1, \dots, 1)$ again showing that $(a_1, a_{k-1}, b_k, 1, \dots, 1) \in A$ since,

$$C((a_1, a_{k-1}, b_k, 1, \dots, 1)) \leq C((a_1, a_{k-1}, b'_k, \dots, b'_k - 1, \dots, b'_u))$$

for any $b'_k > 1$. $(a_1, \dots, a_{k-1}, b'_k, [12] \dots, b'_u)$ cannot be a smaller neighbor of the following type: $(a_1, \dots, a_{k-1}, b'_k, \dots, b'_k - 1, b'_u)$. ■

2 Counting in a Slice of V

Set $\bar{V} = \{P \in V \mid X_i(P) \leq X_{i+1}(P), 1 \leq i < u\}$. For every point P in V , we denote by \bar{P} a point whose coordinates are same the coordinates of P , but are in ascending order. Thus we have a map $\bar{\cdot} : V \rightarrow \bar{V}$. Denote the image of a set S under this map by \bar{S} .

The following properties are easy to prove;

Proposition 2.1 1. For any $I \in V$, there exists a $\sigma \in S_u$ such that $\sigma(I) = \bar{I}$.

2. $C(P) = C(\bar{P})$.

3. $\cup_{\sigma \in S_u} \sigma(\bar{V}) = V$.
4. If P is a neighbor to Q , then \bar{P} is a neighbor to \bar{Q} .
5. If S is connected then \bar{S} is also connected.
6. If P_0 defines P , then \bar{P}_0 defines \bar{P} . Conversely if \bar{P}_0 defines \bar{P} then there exists $\sigma \in S_u$ such that $\sigma(P_0)$ defines P .
7. $P \in \mathfrak{A}$ iff $\bar{P} \in \bar{\mathfrak{A}}$. In other words $\bar{\mathfrak{A}} = \mathfrak{A} \cap \bar{V}$.
8. $\cup_{\sigma \in S_u} \sigma(\bar{\mathfrak{A}}) = \mathfrak{A}$.

Proof We will prove (4). If $\sigma \in S_u$, then $\sigma(P)$ and $\sigma(Q)$ are neighbors. Therefore we can assume that $P = \bar{P}$. Suppose k is an index such that $X_k(Q) = \min\{X_i(Q)\}$. Put $Q' = (1, k)(Q)$. It is enough to prove that $|X_i(P) - X_i(Q')| \leq 1$ for $i = 1$ and $i = k$. Since $P = \bar{P}$, and Q is a neighbor of P we have, $X_1(P) \leq X_k(P) \leq X_k(Q) + 1$. Therefore $X_1(P) - X_1(Q') \leq 1$. Also by the choice of k , $X_1(P) \geq X_1(Q) \geq X_k(Q) - 1$. Thus $|X_1(P) - X_1(Q')| \leq 1$. Again since Q is a neighbor of P and $X_k(Q) \leq X_1(Q)$, $X_k(P) \leq X_k(Q) + 1 \leq X_1(Q) + 1 = X_k(Q) + 1$. Thus $X_k(P) - X_k(Q') \leq 1$. On the other hand, $X_k(P) \geq X_1(P) \geq X_1(Q) - 1 = X_k(Q) - 1$. This shows that $|X_k(P) - X_k(Q')| \leq 1$. This completes the proof.

Lemma 2.2 For any $P \in V$, the cardinality of the set $\{Q \in V \mid \bar{Q} = \bar{P}\}$ is $\binom{u}{r_1, \dots, r_s}$ where,

$$\begin{aligned} r_1 &= \text{repetition of } x_1(\bar{P}) \\ r_2 &= \text{repetition of } x_{1+r_1}(\bar{P}) \\ &\dots \end{aligned}$$

Proof See second paragraph on page 16 in [?].

Example 2.3 Let $V = \{(x_1, x_2, x_3, x_4) \mid x_i \in \mathbb{Z}^+, i = 1, \dots, 4\}$, and $P = (1, 2, 1, 3)$. Then $\bar{P} = (1, 1, 2, 3)$ and $r_1 = 2, r_2 = 1, r_3 = 1$, and

$$|\{Q \in V \mid \bar{Q} = \bar{P}\}| = \binom{4}{2, 1, 1} = \frac{4!}{2!1!1!} = 12.$$

Definition 2.4 Slice anchor points are $A_+ = A \cap \bar{V}$, where A is the set of anchor points.

It is clear that $\langle A_+ \rangle = A$.

Definition 2.5 Constant $\binom{u}{r_1, \dots, r_s}$ associated with any point Q is called the permutation degree (p -degree) of Q .

Lemma 2.6 Suppose $Q_1, Q_2 \in \bar{V}$ are such that $x_i(Q_i) \leq x_i(Q_2)$, $1 \leq i \leq u$ and $C(Q_1) < T$, $C(Q_2) \geq T$. Then there exists $P \in \bar{\mathfrak{A}}$, such that $x_i(Q_1) \leq x_i(P) \leq x_i(Q_2)$.

Proof We use induction on $m = \sum_{i=1}^u [x_i(Q_2) - x_i(Q_1)]$. If $m = 1$, then $Q_2 \in \bar{\mathfrak{A}}$ and we are done. Suppose j is a maximum index such that $x_j(Q_1) \neq x_j(Q_2)$. Set $Q = (x_1(Q_1), \dots, x_j(Q_1)+1, \dots, x_u(Q_1))$. Now, $x_j(Q_1) < x_j(Q_2) \leq x_{j+1}(Q_2) = x_{j+1}(Q_1)$. So, $x_j(Q_1)+1 \leq x_{j+1}(Q_1)$. Hence $x_j(Q) \leq x_{j+1}(Q)$. Therefore, $Q \in \bar{V}$. If $C(Q) \geq T$, then $Q \in A_+$. If $C(Q) < T$, then since

$$\sum_{i=1}^u [x_i(Q_2) - x_i(Q_1)] \leq \sum_{i=1}^u [x_i(Q_2) - x_i(Q_1)] + 1$$

by induction there exists a $P \in \bar{\mathfrak{A}}$ with required property.

The above lemma gives us a faster algorithm to compute $\bar{\mathfrak{A}}$. We first find $\bar{\mathfrak{A}}$ and then take permutations of all points to construct \mathfrak{A} . For finding $\bar{\mathfrak{A}}$, we define the following order on the points of V , $I \leq J$ if $|I| < |J|$ or $|I| = |J|$ and $x_u(I) < x_u(J)$ or $|I| = |J|$, $x_i(I) < x_i(J)$ and $x_j(I) = x_j(J) \forall j > i$. Then as before, we consider $X = \{(i, i, \dots, i) | 1 \leq i \leq n\}$ and apply lemma 2.6 to find an *anchorpoint*. The following algorithm uses this technique.

Lemma 2.7 Suppose $(a_1, \dots, a_r, \dots, a_u) \in \bar{\mathfrak{A}}$ has the following property:

$$a_r = \max\{x_r(P) \mid x_i(P) = a_i, i = 1, \dots, r-1, P \in \bar{\mathfrak{A}}\}$$

Suppose $Q \in \bar{V}$ is such that, $x_i(Q) = a_i$ for $1 \leq i < r$ and $x_r(Q) > a_r$, Then $C(Q) > T$.

Proof Suppose $(a_1, \dots, a_r, \dots, a_u) \in A_+$ had the property given in the hypothesis and

$(b_1, \dots, b_u) \in \bar{V}$ with $a_i = b_i$ for $1 \leq i < r$ and $b_r > a_r$. We claim that $C(b_1, \dots, b_u) \geq T$.

We prove this by contradiction. Suppose $C(b_1, \dots, b_u) < T$. Set $Q = (a_1, \dots, a_{r-1}, b_r, c_{r+1}, \dots, c_u)$ with $c_i = \max(a_i, b_i)$, $r+1 \leq i \leq u$. Note that $b_r = \max(a_r, b_r) \leq \max(a_{r+1}, b_{r+1})$ since $a_r \leq a_{r+1}$ and $b_r \leq b_{r+1}$. Thus $Q \in \bar{V}$. Further, $x_i(Q) \geq b_i \forall i$ and $C(Q) \geq C(a_1, \dots, a_u) \geq T$. Hence by Lemma 2.6, there exist $P \in A_+$ with $x_i(Q) \geq x_i(P) \geq b_i$. But for $1 \leq i < r$, $x_i(Q) = b_i = a_i$ and $x_r(Q) = b_r$. Thus we have an anchor point P with $x_i(P) = a_i$, $1 \leq i < r$ and $x_r(P) > a_r$. This is a contradiction. Thus we must have $C(b_1, \dots, b_r) \geq T$.

Conversely,

Lemma 2.8 For any $Q \in \{\bar{V} \setminus \bar{A}\}$ with $C(Q) > T$, there exists $(a_1, \dots, a_r, \dots, a_u) \in \bar{\mathfrak{A}}$, such that, $x_i(Q) = a_i$, for all $1 \leq i \leq r-1$ and $x_r(Q) > a_r$.

Proof Suppose $(b_1, \dots, b_u) \in \{\bar{V} \setminus \bar{\mathfrak{A}}\}$ with $C(b_1, \dots, b_u) \geq T$. Choose a point $(a_1, \dots, a_r, \dots, a_u) \in \bar{\mathfrak{A}}$ such that r is a maximum integer such that $a_i = b_i$, $1 \leq i < r$ and $a_r \neq b_r$. This condition is vacuous if $r = 1$. We claim $a_r < b_r$.

We prove by contradiction. Suppose $a_r > b_r$. Set $Q = (a_1, \dots, a_{r-1}, b_r, c_{r+1}, \dots, c_u)$ with $c_i = \min(a_i, b_i)$. It is easy to show that $Q \in \bar{V}$. Since $C(Q) \leq C(a_1, \dots, a_u)$, for any j ,

$$C(x_i(Q), \dots, x_j(Q) - 1, \dots, x_u(Q)) \leq C(a_1, \dots, a_j - 1, \dots, a_u)$$

If $(a_1, \dots, a_u) \in \bar{\mathfrak{A}}$, then there exists j such that $C(a_1, \dots, a_j - 1, \dots, a_u) < T$ by definition of anchor point. Hence, $C(x_i(Q), \dots, x_j(Q) - 1, \dots, x_u(Q)) < T$. Thus if $C(Q) \geq T$, then Q is an anchor point, which contradicts the minimality of r . Thus $C(Q) < T$. Also $x_i(Q) \leq b_i$. Now we use Lemma 2.6 to find $P \in \bar{\mathfrak{A}}$, such that $x_i(Q) \leq x_i(P) \leq b_i$. Since $x_i(Q) = b_i = a_i$, $1 \leq i \leq r$ and $x_r(Q) = b_r$, we found $P \in \bar{\mathfrak{A}}$ such that $x_i(P) = b_i$ for $1 \leq i \leq r$. This violates the maximality of r s. Thus we must have $a_r < b_r$.

Definition 2.9 Let $(a_1, \dots, a_r, \dots, a_u) \in \bar{\mathfrak{A}}$ be an anchor point of Lemma 2.7. Consider,

$$\tau(a_1, \dots, a_r) = \{P \in V \mid x_i(\bar{P}) = a_i, 1 \leq i < r, \text{ and } x_r(\bar{P}) > a_r\}$$

Lemma 2.10 Suppose $P_1, P_2 \in \bar{\mathfrak{A}}$ are such that,

$$x_r(P_1) = \max \{x_r(Q) \mid x_i(Q) = x_i(P_1), 1 \leq i < r, Q \in \bar{\mathfrak{A}}\}$$

$$x_s(P_2) = \max \{x_s(Q) \mid x_i(Q) = x_i(P_2), 1 \leq i < s, Q \in \bar{\mathfrak{A}}\}$$

Then $\tau(x_1(P_1), \dots, x_r(P_1))$ and $\tau(x_1(P_2), \dots, x_s(P_2))$ are disjoint or identical.

Proof We will show that if (c_1, \dots, c_u) is in,

$$\tau(x_1(P_1), \dots, x_r(P_1)) \cap \tau(x_1(P_2), \dots, x_s(P_2))$$

then $x_i(P_1) = x_i(P_2)$ for $r = s$ and $1 \leq i \leq r$.

We can assume that $r \leq s$. If $r < s$, then we have $x_r(P_1) \geq x_r(P_2)$ since $x_i(P_1) = x_i(P_2) = c_i$ for $1 \leq i < r$. However by Lemma 2.8 we know that $x_r(P_1) < c_r = x_r(P_2)$. This is a contradiction. Hence we must have $r = s$ and $x_r(P_1) = x_r(P_2)$.

Lemmas 2.7 and 2.10 show that for the right choices of $\{a_1, \dots, a_r\}$, $1 \leq r \leq u$,

$$\{Q \in \bar{V} \mid C(Q) \geq T\} \equiv \bar{\mathfrak{A}} \bigcup_{(a_1, \dots, a_r)} \tau(a_1, \dots, a_r)$$

Lemma 2.11 Let $1 \leq a_1 \leq a_2 \leq \dots \leq a_r \leq n$ with $r \leq u$. Define,

$$\tau(a_1, \dots, a_r) = \{P \in \bar{V} \mid x_i(P) = a_i, 1 \leq i \leq r \text{ and } x_r(P) > a_r\}$$

and $f(r_1, \dots, r_s)$ is the number of points P with $x_1 P$ repeated r_1 times, $x_{r_1+1}(P)$ repeated $r_2, \dots, x_{r_1+r_2+\dots+r_{s-1}+1}(P)$ repeated r_s times, then

$$\binom{f(r_1, \dots, r_s) = k_1}{s \binom{k_2}{s-1}}$$

$k_1 = u - r$ and $k_2 = u - n$.

3 Counting Points in Slice

Algorithm 1 illustrates the algorithm used to compute the points with cost $\geq T$ in V using only $\bar{\mathfrak{A}}$. Below we give some definitions and formulae used in the Algorithm 1.

Definition 3.1 If $part_u = \{\text{partitions of } u\}$, then for $E \in part_u$, $E = s_1^{p_1} s_2^{p_2} \dots s_r^{p_r}$. Also,

$$E_n = \sum_{i=1}^r p_i \quad (1)$$

$$mult_E = \binom{E_n}{p_1, \dots, p_r} \quad (2)$$

$$perm_E = \binom{u}{\underbrace{s_1, s_1 \dots}_{p_1} \dots \underbrace{s_r, s_r \dots}_{p_r}} \quad (3)$$

Let,

$$F_u = \sum_{E \in part_u} mult_E \times perm_E \times D_F \quad D_F = \begin{cases} 1 & E_n = 1, 2 \\ 0 & \text{otherwise} \end{cases} \quad (4)$$

$$R_u = \sum_{E \in part_u} mult_E \times perm_E \times D_R \quad D_R = \begin{cases} 1 & E_n = 2, 3 \\ 0 & \text{otherwise} \end{cases} \quad (5)$$

$$Q_{j, E_n} = \begin{cases} 0 & E_n < 3 \\ \frac{1}{(E_n - 3)!} & E_n = 3 \\ \frac{1}{(E_n - 3)!} \prod_{m=0}^{E_n-4} (j - E_n + 3 + m) & \text{otherwise} \end{cases} \quad (6)$$

Algorithm 1 *Anchor2PointsSlice*(S, n, r)

- 1: $\{S$ is the $k \times U$ matrix of k of slice anchor points}
 - 2: $\{n$ is the max value of any element in an anchor point}
 - 3: $\{r$ is a 2×2 matrix where $[rs \ cs; re \ ce]$ define the upper left hand corner (rs, cs) and (re, ce) define the lower right hand corner of the space in $\bar{\mathfrak{A}}$ that is currently being processed}
 - 4: $result = \text{Anchor2PointsSliceRecur}(S, n, r)$
 - 5: **for all** p , slice anchor point in S **do**
 - 6: $result = result + \text{permutation degree of } p$
 - 7: **end for**
 - 8: return $result$
-

Anchor2PointsSliceRecur
f
MakeGroups

Algorithm 2 *Anchors2PointsSliceRecur*(S, n, r)

- 1: { S is the $k \times U$ matrix of k of slice anchor points}
- 2: { n is the max value of any element in an anchor point}
- 3: { r is a 2×2 matrix where $[rs \ cs; \ re \ ce]$ define the upper left hand corner (rs, cs) and (re, ce) define the lower right hand corner of the space in A that is currently being processed}
- 4: {If the final value of a summation variable is smaller than its initial value, let that summation be zero.}
- 5: **if** S is empty **then**
- 6: return 0
- 7: **end if**
- 8: $[rs \ cs; \ re \ ce] \leftarrow r$
- 9: **if** $ce > cs$ **then**
- 10: $r1 = \text{makegroups}(A, r)$
- 11: **for all** ri such that ri is a 2×2 group specification in $r1$ **do**
- 12: $result = result + \text{Anchors2PointsSliceRecur}(S, n, ri)$
- 13: **end for**
- 14: **end if**
- 15: $f_{max} = \max(cs^{th} \text{ column from rows } rs \text{ to } re \text{ in } A)$
- 16: $u = ce - cs + 1$
- 17: **while** $fi \leq n$ **do**
- 18: $fsum = fsum + f(fi, u, n)$
- 19: $fi = fi + 1$
- 20: **end while**
- 21: $k = n - f_{max} - 1$
- 22: { F_u, R_u and Q_{j, E_n} below are from Equation (4), (5) and (6) respectively.}
- 23:

$$fsum = 1 + kF_u + \frac{(k-1)k}{2}R_u + \sum_{E \in part_u} \left[mult_E \times perm_E \times \sum_{j=2}^{k-1} \left(\frac{(k-j)(k+1-j)}{2} Q_{j, E_n} \right) \right]$$

- 24: $d = \text{denominator of multinomial coefficient of } S(re, 1), S(re, 2), \dots, S(re, cs-1)$
 - 25: $rp = \frac{U!}{d \times u!} \times fsum$
 - 26: **return** $result + rp$
-

Algorithm 3 $f(fi, u, n)$

- 1: $\{fi$ is coordinate value to process $\}$
- 2: $\{u$ is number of axes after and including fi $\}$
- 3: $\{n$ maximum coordinate value $\}$
- 4: $\{\text{In the computation of } count, \text{ if the starting condition of the product is greater than the ending condition, then } count = 0.\}$
- 5: $k = n - fi, result = 0$
- 6: **if** $k \leq 0$ **then**
- 7: return 0
- 8: **end if**
- 9: **for all** $E = s_1^{p_1} s_2^{p_2} \dots s_r^{p_r}$, partition of u **do**
- 10: $mul = \binom{r}{p_1, \dots, p_r}$
- 11: $perm = \binom{u}{\underbrace{s_1, s_1, \dots, s_1}_{p_1} \dots \underbrace{s_r, s_r, \dots, s_r}_{p_r}}$
- 12: $t = p_1 + p_2 + \dots + p_r$
- 13:

$$count = \begin{cases} 1 & \text{if } t = 1; \\ k & \text{if } t = 2; \\ \sum_{l=t-2}^{k-1} \left[\binom{1}{t-3} \prod_{m=0}^{t-4} (l - t + 3 + m) \right] (k - l) & \text{otherwise.} \end{cases}$$

- 14: $result = result + (mul \times perm \times count)$
 - 15: **end for**
 - 16: return $result$
-

Algorithm 4 $MakeGroups(A, r)$

- 1: $\{A$ is the $k \times U$ matrix of k of anchor points $\}$
 - 2: $\{r$ is a 2×2 matrix where $[rs \ cs; \ re \ ce]$ define the upper left hand corner (rs, cs) and (re, ce) define the lower right hand corner of the space in A within which groups are to be made $\}$
 - 3: $[rs \ cs; \ re \ ce] \leftarrow r$
 - 4: $ri \leftarrow rs$
 - 5: **while** $ri \leq re$ **do**
 - 6: Record $[ri \ (cs + 1)]$ as beginning of group
 - 7: $fe \leftarrow A(ri, cs + 1)$
 - 8: **while** $ri \leq re$ **do**
 - 9: **if** $fe = A(ri, cs + 1)$ **then**
 - 10: $rf \leftarrow ri$
 - 11: $ri \leftarrow ri + 1$
 - 12: **end if**
 - 13: **end while**
 - 14: Record $[rf \ ce]$ as end of group
 - 15: **end while**
 - 16: return all groups
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